

Embodied AI Standardization: Chinese approach

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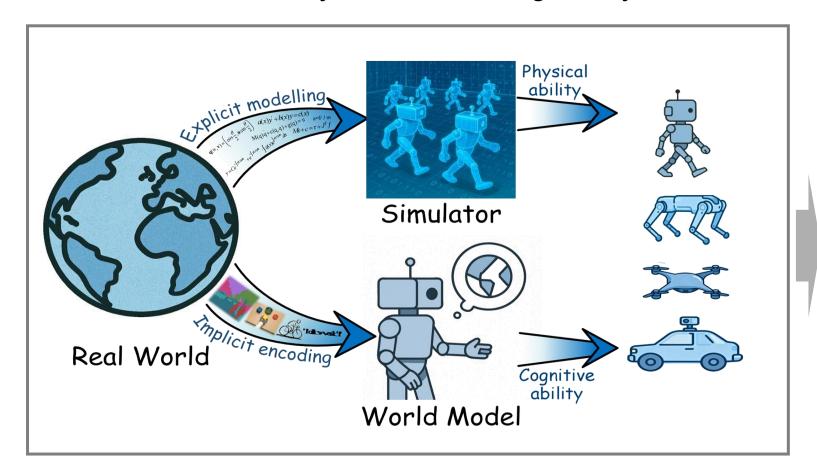


- 1. Physical AI, also referred to as embodied AI
- 2. Technical Challenges
- 3. The Role of Standardization

Physical AI ≈ embodied AI



Embodied AI and Physical AI almost align in key features.



What it is?

AI + physical body

How it works?

interact with the physical world

Where it applies?

robots, autonomous vehicles (AVs) and other physical systems.

What it can do?

perception, cognition, and action

Subtle differences:

- Physical AI emphasizes the simulation and understanding of physical laws.
- Embodied AI emphasizes act autonomously and adapting to the physical world

Physical AI, also referred to as embodied AI





Embodied AI refers to the integration of artificial intelligence into physical systems, enabling them to interact with the physical world. These systems can include general-purpose robots, humanoid robots, autonomous vehicles (AVs), and even factories and warehouse facilities.

Physical AI lets autonomous systems like cameras, robots, and self-driving cars perceive, understand, reason, and perform or orchestrate complex actions in the physical world. Physical AI is unlocking new capabilities that will transform every industry like robots, autonomous vehicles (AVs) and smart space.

Known as physical AI or embodied AI, this convergence of robotics and artificial intelligence is poised to redefine how machines interact with humans and their environments.

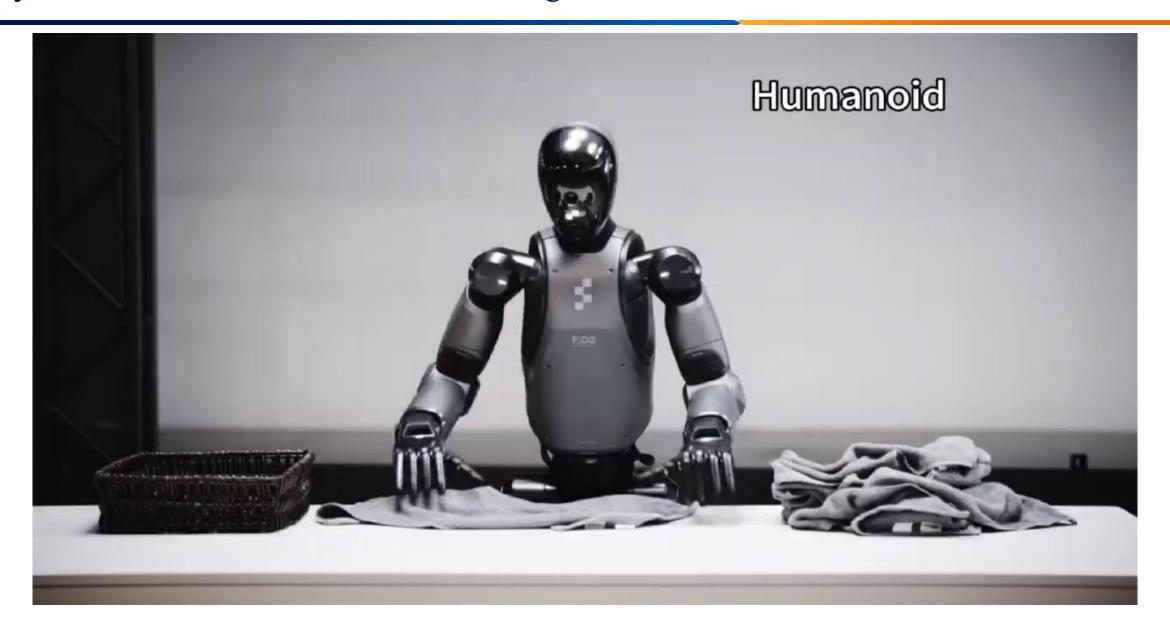
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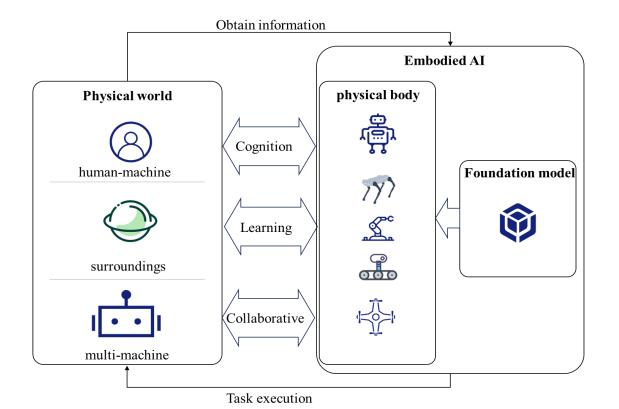
"Physical AI" refers to embodied artificial intelligence that acquires and develops intelligence through direct interaction with the physical environment via components such as sensors and actuators.







Conceptual diagram and key features



Definition

Embodied artificial intelligence(EAI): Artificial intelligence integrated into physical systems that interact autonomously with, and adapt to the physical world.

ITU-T F.RF-EAI "Requirements and framework for embodied artificial intelligence systems"

Embodied AI: beyond AI and robotics









1973 WABOT-1



1999 AIBO



2000 ASIMO

Smart Robot

Sensory & Execution







Embodied AI

- Sensory & Execution
- Cognition
- Collaborating
- Learning

Robot

Programmed

Humanoid Robot

- Robot with body, head and limbs
- looking and moving like a human

Embodied AI and (Non-embodied) AI



Embodied AI is a transformative shift in AI that integrates AI into physical systems, enabling them to interact with and learn from their environment through sensory inputs and actions.

Aspect	(Non-embodied) AI (ChatGPT, Image Recognition program)	Embodied AI (Robots, Self-driving Cars)	
Form of Existence	"A Brain in a Vat": Pure software, residing on servers.	"An Embodied Brain": Software integrated with a physical body.	
Primary Goal	Process information in a digital space; passively waits for input (e.g., a prompt).	Take action in a physical environment; acts proactively based on the situation.	
Input/Output	Data (text, images, speech)/Data (generated text, classification labels)	Perception (sensor data, cameras, LiDAR, touch)/Action (movement, manipulation)	
Learning Paradigm	Learns from static datasets: Trained by analyzing massive existing collections of images and text.	Learns through interaction & experience: Learns like an infant, through trial and error, touching, observing, and failing.	

Embodied AI = AI + Physical Body (Action)

Embodied AI and robotics



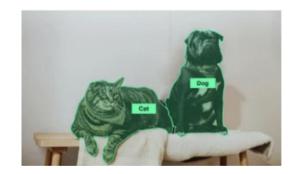
Embodied AI enables robots from automation to autonomy, allowing them to performs behaviours or tasks independently, learn, and adapt to changing environments.

Perspective	Robotics	Embodied AI	
1. From "Programming" to "Learning"	All behaviors are based on explicit code written by programmers.	Abilities are acquired through real-time environmental interaction (trial-and-error).	
2. From "Perception for Action" to "Perception-Cognition-Action"	Sensory data is used directly to execute predefined actions. e.g., verifying workpiece position, performing force-controlled assembly.	Sensory data is used to construct an internal model of the world, (e.g., "This is a messy room") and object properties, enabling actions driven by cognition.	
3. From "Closed World" to "Open World"	The environment and all variables (e.g., object location, lighting, process) must be predictable and pre-defined.e.g., verifying workpiece position, performing force-controlled assembly.	Its purpose is to cope with environments, and must handle unseen objects, adapt to dynamic changes, and deal with ambiguity.	

Embodied AI = Robots + Brain (Cognition)

Key capabilities of embodied AI





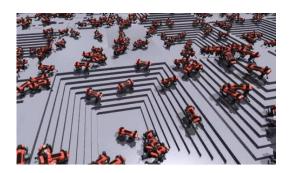
Recognition



1.Cognition



Programming



2.Learning



Isolated





3.Collaborative

EAI is a promising path to achieve AGI





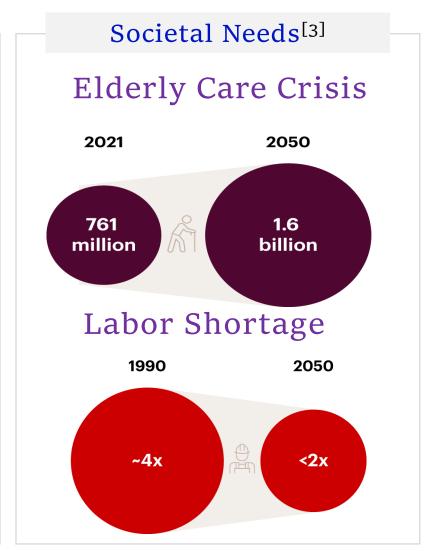
\$ 38 Billion

by 2035^[1]

1 Billion in Use

by 2050^[2]

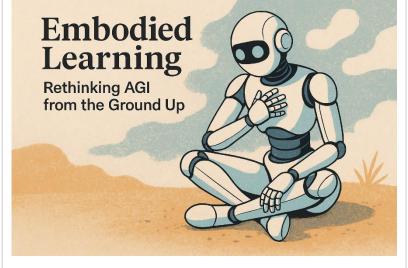
only for humanoid robots



The way towards AGI

读万卷书, 行万里路

Read ten thousand books, travel ten thousand miles.



[1]Goldman Sachs, Jan, 2024, Global Automation: Humanoid Robots – The AI Accelerant [2]Morgan Stanley, May 2025, Humanoids: A \$5 Trillion Market [3]UN Department of Economic and Social Affairs & International Labor Organization



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Moravec's paradox is still valid for EAI



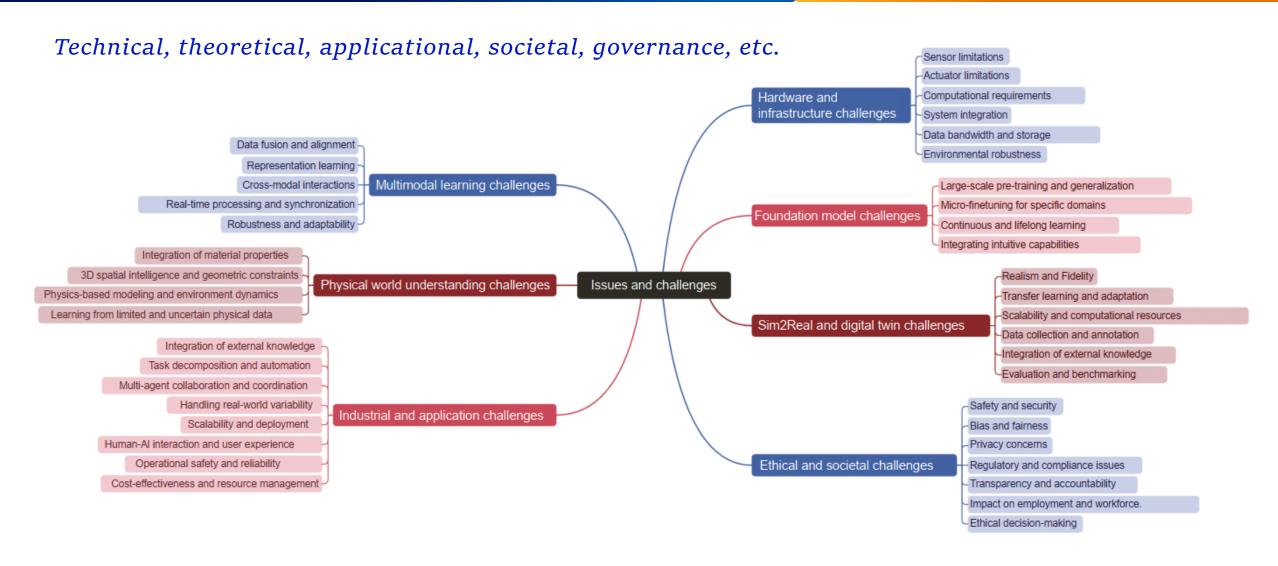
"It is comparatively easy to make computers exhibit adult level performance on intelligence tests or playing checkers, and difficult or impossible to give them the skills of a one-year-old when it comes to perception and mobility."

——Hans Moravec, 1988



There are many challenges ahead...





Sources: Sun F, Chen R, Ji T, et al. A comprehensive survey on embodied intelligence: Advancements, challenges, and future perspectives[J]. CAAI Artificial Intelligence Research, 2024, 3: 9150042.



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EAI standardization gap analysis



Dimension	Key Challenges	Standardization Directions		
1. Data & Perception	 Heterogeneous multimodal and multimedia data Lack of high-quality, task-specific datasets 	 Format and quality standard for Multimodal training data Benchmark dataset & annotation specifications 		
2. Network & Collaboration	 Complex task allocation across cloud-edge-device Lack of common multi-agent communication protocols 	Unified interfaces for collaborative computingStandardized real-time agent interaction protocols		
3. Model & Evaluation	No unified benchmarks for embodied models	Assessment criteria and metricsStandardized performance benchmarks		
4. System Integration	 High complexity in integrating heterogeneous components Poor interoperability between vendors 	 Modular development frameworks Plug-and-play component & middleware standards 		
5. Human-Robot Interaction	 Lack of safety protocols for physical HRI Inconsistent user interfaces and experiences 	Safety standards for physical interactionHuman-centered design guidelines		
6. Safety & Security	Data privacy and protection risksLack of algorithmic transparency and explainability	End-to-end security & privacy frameworksStandards for explainable EAI & audit trails		
7. Ethics & Governance	Ambiguity in accountability and liabilityRisk of value misalignment	Accountability & liability frameworksEthical guidelines & compliance standards		

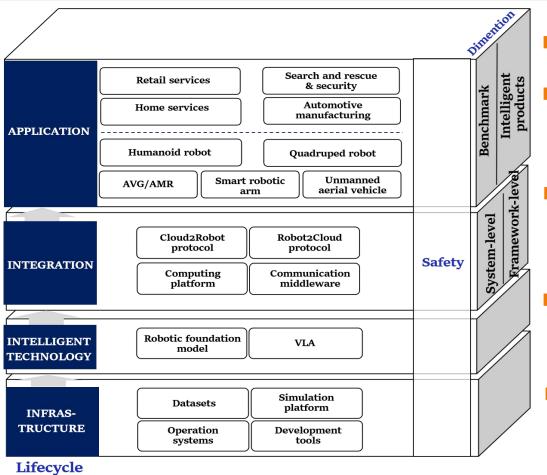
MIIT TC1 focuses on Chinese standardization work





Artificial Intelligence Standardization Technical Committee of the Ministry of Industry and Information Technology

MIIT/TC1 has developed a standardization roadmap for EAI



- Application Capability requirements for embodied artificial intelligence home companion products
- Application 2024-1328T-YD The benchmarking and assessment method for embodied artificial intelligence
- Safety Requirements for risk prevention capabilities in human-machine interaction of embodied artificial intelligence systems
- Data Capability assessment guide for embodied artificial intelligence training grounds
- Data 2024-1329T-YD Dataset quality requirements and evaluation methods of embodied artificial intelligence



EAI Bench: Industry-oriented embodied AI benchmark: tackling diversity scenarios, disunified tasks, and inconsistent evaluation criteria.

ONE Assesment Standard

ONE Set of Test Tasks

Standardized Testing
Environment

Jointly built with industry under unified data standards to ensure the assessment tasks are scalable, industry-relevant, and widely applicable.

The first co-built Test datasets cover 2,000 test tasks, covering 300 task types across manufacturing, household, retail, and logistics scenarios.

Goal: Co-develop an industry-oriented test set with a unified evaluation criterion, conducting real-world assessments in a standardized environment to accelerate embodied AI from training to practical use.



ITU-T SG21's contribution





ITU-T is focusing on EAI and has started working on standards.

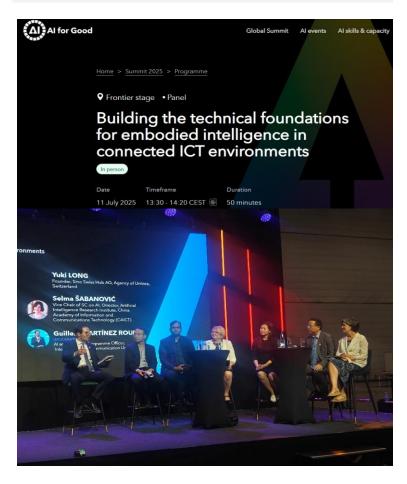
- ITU-T F.748.66 Requirements and framework for embodied artificial intelligence systems
- ITU-T F.TR-ED Technical requirements for embodied artificial intelligence teleoperation data collection systems in real-world scenarios
- ITU-T F.BA-EAI Framework for benchmarking and assessment of embodied artificial intelligence systems

application layer	application scenarios service interfaces, user/task-oriented services					
functional layer	embodied perception multi-modal perception environment perception dynamic perception	embodied decision- making task planning decision optimization	embodied execution locomotion manipulation	human-machine interaction multi-machine collaboration	embodied learning	
basic layer	foundation me	odel	computing platform		machine	

ITU-T's efforts on EAI standardization



AI for Good Pannel



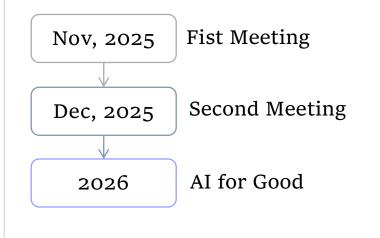
Embodied AI Workshop





AHG-EAI

Explore possible approaches to advancing Embodied AI standards or pre-standards work.



Standards are essential in translating the values we agree on as a global community into real-world systems.

Standards should not be construed as constraints on innovation.

The way forward for standardization for AI for Good



- Embodied AI represents a promising pathway toward AGI that goes beyond the current domains of AI and robotics, with the potential to benefit humanity greatly.
- Moravec's paradox is still valid; EAI faces significant challenges, some of which can be effectively addressed through standardization.
- International cooperation in embodied intelligence standards is crucial.
- I hope to continue the discussions on EAI international standards at the International AI Standards Summit in Korea next month.



Thanks

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